

Embedded Training Equipment

Al Mavin I





Embedded Training Equipments Al Mavin II

Training Contents

Embedded System

Embedded System Overview Application Areas of Embedded System Embedded Hardware Embedded Linux

Practice Environment

Al Mavin Network Connection between PC and Al Mavin Development Environment Equipment Boot Media Kernel Source Code

Linux Kernel Module

Module Programming Kernel Module Implementation Kernel Debugging LED Control using Kernel Module Switch Status Check using Kernel Module

Linux Kernel API

Linked List Queue

Process Management and Scheduling Memory Allocation and Deallocation User Level Direct Memory Access Kernel Timer

Kernel Thread Interrupt **Export Symbol**

Linux Kernel Driver

Virtual File System Character Device Driver Misc Device Driver Device Tree Platform Device Driver I²C Device Driver SPI Interface Shared Library

Image Processing

Computer Vision OpenCV OpenCV with CSI Camera Motion Detect Color Detect Face Detection

Cayout





Component





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Platform USB (include OS image and Tools)



Programming Cable



12V 5A Adaptor



Micro SD Adapter





User Guide book



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- ARM Cortex-A based high-performance embedded system training Equipment for Linux-based device driver implementation and application
- Main module is an edge supercomputer with a built-in GPU of up to 21 TOPS level. Applications support popular A frameworks such as TensorFlow2, PyTorch, Caffe/Caffe2, MXNet, Keras, etc.
- Integrated configuration of main module that supports CUDA artificial intelligence acceleration calculation, speaker, digital array microphone, camera, high-precision environmental sensor, and breadboard
- User circuit configuration is possible through a breadboard, and application sensor modules are provided to integrate with the ARM Cortex-M processor
- High-resolution dual CSI camera with adjustable angle to enable image processing and deep learning-based vision processing learning is provided
- Gigabit Ethernet, dual-band Wi-Fi, and Bluetooth for IoT service to support PLC equipment and OPC-UA communication
- Support for MQTT-based IoT connectivity, OpenCV-based image processing, and QT-based GUI practice in conjunction
 with device driver
- Support Xeus-python and Cling interpreter for aarch64 and VSCode-based IDE to enable learning C/C++ and Python 3
- Linux kernel configuration and build, system call, platform device driver, MISC device driver, and application program
 implementation contents are provided

Operating Program

	List	Specifications
Linux OS	Desktop	X-Server, Openbox, LightDM, Tint2, blueman, network-manager, conky
	CLI	Zsh, Oh-My-Zsh with powerlevel9k thema and nerd fonts, Tmux, fzf, bat, lsd
	Tool Chain	Python3, NodeJS, Java, Clang, GCC, LLVM
	IDE	Visual Studio Code, Jupyter Lab, NeoVim
	Connectivity	Remote Desktop Server with NoMachine, MQTT Broker with mosquitto, Jupyter Lab Server Bluez, paho-mqtt
	Multimedia	portaudio. sox, OpenCV, Google Assistant
	Data Science & Al	Python3, Numpy, Matplotlib, sympy, Pandas, Seaborn, Scipy, Gym Scikit-learn, Tensorflow, Keras
Pop Library	Output Object	Led, Laser, Buzzer, Relay, RGBLed, DCMotor, StepMotor, OLed PiezoBuzzer, PixelDisplay, TextLCD, FND, Led Bar
	Input Object	Switch, Touch, Reed, LimitSwitch, Mercury, Knock, Tilt, Opto, Pir, Flame LineTrace, TempHumi, UltraSonic, Shock, Sound, Potentiometer, Cds SoilMoisture, Thermistor, Temperature, Gas, Dust, Psd. Gesture
	Multimedia	AudioPlay, AudioPlayList, AudioRecord, Tone, SoundMeter
	Voice Assistant	GAssistant, create_conversation_stream
	Al	Linear Regression, Logistic Regression, Perceptron, ANN, DNN, CNN, DQN



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Main Module	CPU	6-core ARM v8.2 64-bit 6MB L2 + 4MB L3 Max Freq: 6-core@1900MHz
	GPU	384-core NVIDIA VoltaTM GPU with 48 Tensor Cores Max Freq: 1100MHz
	Memory	8GB 128-bit LPDDR4x@ 1600MHz
	Storage	16GB eMMC 5.1, NVMe 256GB SSD 1ea(M.2)
	Video Encoder	2x464MP/sec(HEVC), 2x4k@ 30(HEVC) 6x 1080p@ 60(HEVC), 14x 1080p@ 30(HEVC)
	Video Decoder	2x690MP/sec(HEVC), 2x4k@ 60(HEVC), 4x4k@30(HEVC) 12x1080p@ 60(HEVC), 32x 1080p@ 30(HEVC), 16x 1080p@30(H.264)
	CSI Camera	Up to 6 cameras(36 via virtual channels) 12 lanes MIPI CSI-2, D-PHY 1.2(up to 30 Gbps)
	Connectivity	Dual Band Wireless WiFi 2GHz/5GHz Band, 867Mbps, 802.11ac Bluetooth 4.2 10/100/1000 Base-T Ethernet
	Display	2 multi-mode DP 1.4/eDP 1.4/HDMI 2.0
	USB	4x USB 3.0, USB 2.0 Micro-B
,	Image Sensor	Sony IMX219
	Resolution	8M pixel native resolution sensor (3280 x 2464 pixel static images)
	Video	1080p30, 720p60 and 640x480p90
	-	V4L2 driver available
Camera	Linux Integration	
	Focal length Horizontal field of view	3.04 mm 62.2 degrees
	Vertical field of view	48.8 degrees
	Focal ratio (F-Stop)	2.0
	High Performance	2.0
	Digital Microphone	4ea
Sound	Sensitivity	-26 dBFS(Omnidirectional)
oddid	Acoustic Overload Point	120dBSPL
	SNR	63dB
	Speaker	2W x 2ea
	GPIO	12 Pin (Alternative Function: I ² C, SPI)
	ADC	8 Pin
Expansion Interface	PWM	16 Pin
Expansion interface	UART	1 Port
	Power	+5V 4 Pin, +3.3V 2 Pin, GND 6 Pin
	BreadBoard	Terminal Strip: 2ea / 350 holes, Distribution Strip: 2ea / 120 holes
	Tiny-F405 Module	+5V, GND, I/O Connector ARM®32-bit Cortex®-M4 CPU CAN, ADC, I ² C, SPI, GPIO etc Mixed CAN 2.0B and CAN FD STDC14 debug connector Serial Wire Debugging(SWD), Virtual COM Port(VCP) support
	Switch Module	Power: +3.3V, GND Input Device: Tact Switch x 4ea(GPIO 4)
	RGB LED Module	Power: +3.3V, GND output device: RGB LED 4ea(GPIO 12)
	Analog Module	Power: +3.3V, GND output device: CdS, NTC, VR(Analog 3)
	TPHG Sensor Module	Power: +3.3V, GND
Expansion Module	Thermopile Sensor Module	Power: +3.3V, GND I/O Interface: I ² C Factory calibrated in wide temperature range: -40 ~ +125°C for sensor temperature and -70 ~ +380°C for object temperature. High accuracy of 0.5°C over wide temperature range (0 ~ +50°C for both Ta and To) High (medical) accuracy calibration Measurement resolution of 0.02°C
	TOF Sensor Module	Power: +3.3V, GND I/O Interface: I ² C 940 nm laser VCSEL Measures absolute range up to 2 m Eye Safe: Class 1 laser device compliant with latest standard IEC 60825-1: 2014 - 3rd edition
	PGCA Sensor Module	Power: +3.3V, GND I/O Interface: I ² C, GPIO Proximity Sensing Gesture Detection RGB Color Sensing & Ambient Light Operating Range: 4-8in (10-20cm) White BackLight LED 4ea(GPIO Control)
	9-Axis Sensor Module	Power: +3.3V, GND I/O Interface: I ² C an advaced triaxial 16bit gyroscope, a versatile, leading edge triaxial 14bit accelerometer and a full performance geomagnetic sensor Gyroscope Range switchable ±125/S to ±2000°/S Low-Pass filter bandwidth 523Hz – 12Hz Accelerometer Range: ±2, ±4, ±8, ±18g Low-Pass filter bandwidth 1kHz – Magnetic field rage typical ±1300uT(x-,y-axis), ±2500uT(z-axis) Magnetic field resolution of ~0.3uT